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Cambra López, M.; Winkel, A.; Mosquera, J.; Ogink, NW.; Aarnink, A. (2015). Comparison between light scattering and gravimetric samplers for PM10 mass concentration in poultry and pig houses. *Atmospheric Environment*. 111:20-27. doi:10.1016/j.atmosenv.2015.03.051.



The final publication is available at

<http://dx.doi.org/10.1016/j.atmosenv.2015.03.051>

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Additional Information

1 **Comparison between light scattering and gravimetric samplers for PM10 mass**
2 **concentration in poultry and pig houses**

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11 **Abstract**

12 The objective of this study was to compare co-located real-time light scattering devices and
13 equivalent gravimetric samplers in poultry and pig houses for PM10 mass concentration, and
14 to develop animal-specific calibration factors for light scattering samplers. These results will
15 contribute to evaluate the comparability of different sampling instruments for PM10
16 concentrations. Paired DustTrak light scattering device (DustTrak aerosol monitor, TSI, U.S.)
17 and PM10 gravimetric cyclone sampler were used for measuring PM10 mass concentrations
18 during 24 h periods (from noon to noon) inside animal houses. Sampling was conducted in 32
19 animal houses in the Netherlands, including broilers, broiler breeders, layers in floor and in
20 aviary system, turkeys, piglets, growing-finishing pigs in traditional and low emission
21 housing with dry and liquid feed, and sows in individual and group housing. A total of 119
22 pairs of 24 h measurements (55 for poultry and 64 for pigs) were recorded and analyzed using
23 linear regression analysis. Deviations between samplers were calculated and discussed. In
24 poultry, cyclone sampler and DustTrak data fitted well to a linear regression, with a
25 regression coefficient equal to 0.41, an intercept of 0.16 mg m⁻³ and a correlation coefficient
26 of 0.91 (excluding turkeys). In pigs, we found a regression coefficient equal to 0.61, an

27 intercept of 0.05 mg m^{-3} and a correlation coefficient of 0.84. Measured PM10 concentrations
28 using DustTraks were clearly underestimated (approx. by a factor 2) in both poultry and pig
29 housing systems compared with cyclone pre-separators. Absolute, relative, and random
30 deviations increased with concentration. DustTrak light scattering devices should be self-
31 calibrated to investigate PM10 mass concentrations accurately in animal houses. We
32 recommend linear regression equations as animal-specific calibration factors for DustTraks
33 instead of manufacturer calibration factors, especially in heavily dusty environments such as
34 animal houses.

35

36 Keywords. Calibration factor, dust measurement, DustTrak, gravimetry, livestock housing.

37

38 **1. Introduction**

39 Appropriate samplers that can provide accurate and comparable particulate matter (PM) mass
40 concentrations are required to ensure compliance with environmental air quality regulations
41 regarding PM emissions from animal houses, and to assess human and animal exposure to
42 PM. Therefore, airborne PM samplers should be able to obtain a representative sample from
43 the original environment at the time of measurement that is consistent with the ‘true’ PM
44 concentration and comparable between devices when tested simultaneously.

45 This still continues to be a challenge in certain environments where the PM under study and
46 the environmental conditions differ from those for which samplers were designed for,
47 especially for sampling devices different from gravimetric. In fact, PM characteristics in
48 animal houses differ from other types of PM because concentrations are generally 10 to 100
49 times higher than in other indoor environments (Zhang, 2004). Concentrations also show
50 different count and mass size distributions compared with ambient air (Lai *et al.*, 2014). In
51 animal house environments, PM comprises heterogeneous particles of different nature, shape,
52 size, density, and chemical composition (Cambra-López *et al.*, 2011b). Cambra-López *et al.*

53 (2011a) reported most particle numbers and mass in pig houses originate from manure, skin,
54 and feed; and in poultry from manure and feathers. A minor part of the particles came from
55 outside (ranging from 0 to 44%, both in numbers and in mass). Lai *et al.* (2014) showed
56 remarkable differences in size of airborne PM among poultry, pig, cattle, and mink housing
57 systems. Moreover, measurement conditions like environmental indoor temperature and
58 relative humidity in animal houses are markedly high compared with outside.

59 Because animal houses' environment and PM characteristics differ considerably from ambient
60 air, research has been conducted to find alternative samplers to the reference samplers for
61 ambient air, to be used in animal houses. Reference samplers include gravimetric
62 measurements prescribed in the United States federal reference method or in the European
63 Union (EU) reference sampler for ambient air. Zhao *et al.* (2009) developed and validated
64 specific gravimetric samplers for PM₁₀ and PM_{2.5} which do not show overloading problems
65 during time-averaged 24 h sampling periods in heavily PM loaded animal houses. The PM₁₀
66 and PM_{2.5} size fractions mainly consist of particles smaller than 10 and 2.5 μm in diameter,
67 respectively. These specific samplers incorporated an inlet head with a cyclone pre-separator
68 (besides the filter holder), which used centrifugal forces to separate large particles, instead of
69 the greased impactor pre-separator specified in the EU reference sampler and described in
70 CEN-EN 12341 (CEN, 1998) for PM₁₀ and in CEN-EN 14907 (CEN, 2005) for PM_{2.5}. The
71 developed samplers by Zhao *et al.* (2009) proved to be equivalent with the EU reference
72 PM₁₀ and PM_{2.5} samplers for low PM concentrations ($< 100 \mu\text{g m}^{-3}$) and for high PM₁₀
73 concentrations when a correction factor was used. Their study also proved that the PM_{2.5}
74 reference sampler became overloaded in the dusty environment of animal houses.

75 Besides gravimetric samplers, real-time samplers, such as light scattering photometers are
76 being widely used because they are suitable for monitoring changes in PM concentrations
77 over a period of time where time-averaged measurements assessed gravimetrically are
78 insufficient. Light scattering photometers measure mass concentration of particles in an air
79 stream as a function of the light scattered by the sampled PM. The relationship between this

80 light scattered and the PM mass concentration depends on the physics of the interaction
81 between the light and the particle: particularly on the incident light, the geometry of the
82 detecting optical system, and particle characteristics (refractive index, shape, density, and
83 size) (Görner *et al.*, 1995; Vincent, 2007). The relationship between this light scattered and
84 the PM mass concentration is usually pre-set in the factory, using a standard type of dust with
85 known physical properties (like coal dust or ISO 12103-1 A1 test dust, Arizona Road Dust).
86 When a light scattering sampler is used to measure PM that differs from the manufacturer's
87 factory calibration PM, substantial sampling bias may occur. Therefore, it is essential to either
88 re-calibrate the instrument with the PM under study, or to adjust data with a specific
89 calibration factor, in order to obtain accurate absolute PM mass concentrations (Heal *et al.*,
90 2000; Kingham *et al.*, 2006).

91 Although light scattering samplers have been used to quantify absolutely PM concentrations
92 and emissions in animal houses (Costa and Guarino, 2009; Roumeliotis *et al.*, 2010;
93 Roumeliotis and Van Heyst, 2007), further research is needed to validate light scattering
94 samplers against gravimetric methods in animal houses to obtain accurate absolute values.
95 Yanosky *et al.* (2002) reported that light scattering samplers should be validated using co-
96 located, well characterized methods to determine the correction equation for bias reduction,
97 and encouraged further investigation on other influencing factors such as changes in particle
98 characteristics. In animal environments, this should be done by comparison with the
99 equivalent gravimetric sampler which is more suitable for animal houses, because it is less
100 vulnerable for overloading (Zhao *et al.*, 2009). Van Ransbeeck (2013) compared a specific
101 light scattering system among other techniques for sampling PM10 in fattening pig's house
102 and proved equivalence compared with EU reference sampler described in CEN-EN 12341
103 (CEN, 1998). Similar comparison tests and investigations are encouraged in other animal
104 housing systems in comparison with the equivalent gravimetric sampler described in Zhao *et*
105 *al.* (2009).

106 Therefore, the objective of this study was to compare co-located real-time light scattering
107 devices and the equivalent gravimetric sampler in poultry and pig houses for PM10 mass
108 concentration and to develop animal-specific calibration factors for light scattering samplers.
109 This study is part of a national field survey conducted in the Netherlands from 2008 to 2011
110 to obtain emissions of most relevant aerial pollutants in animal houses, including inhalable
111 PM, PM10, PM2.5, ammonia, odor, methane and nitrous oxide. A total of 36 animal houses,
112 covering 13 types of housings (for poultry, pigs, dairy cattle, and minks) were surveyed. An
113 overview of the project, sampling methods and emission factors for PM is described in
114 Winkel *et al.* (2014). Data from PM10 concentration measured using light-scattering devices
115 and gravimetric samplers collected during this survey in poultry and pig houses is presented
116 and analyzed in our study. These results will contribute to evaluate the comparability of
117 different sampling instruments for PM10 concentrations.

118 **2. Materials and Methods**

119 **2.1. Light scattering sampler**

120 Mass concentrations of PM10 using the light scattering principle were determined with
121 DustTraks (DustTrak aerosol monitor, model 8520, TSI, Inc., Shoreview, Minn., U.S.).
122 DustTrak is a portable, hand-held device which uses a 90-degree light scattering to measure
123 mass concentration of particles in an air stream that passes through an impactor at an airflow
124 rate of 1.7 L min⁻¹. The PM10 inlets were used in this study. The PM10 fraction is defined as
125 the sampling cut-off diameter of particle separators that the mass of total suspended particles
126 have to pass, for a separation or sampling efficiency of 50%. This varies with the type of
127 sampler and sampling efficiency. DustTraks were cleaned and zero-calibrated before each
128 measurement. Recorded one-minute values were summarized into 24 h averages to compare
129 with gravimetric samplers. DustTraks were factory calibrated using standard ISO 12103-1
130 Arizona Road Dust.

131 The detection range of DustTraks was from 0.001 to 100 mg m⁻³ for particles from 0.1 to 10
132 µm in diameter, with a resolution of ±0.1% of reading or ±0.001 mg m⁻³, whichever is greater
133 (TSI, 2002).

134 **2.2. Gravimetric sampler**

135 Concentrations of PM₁₀ were measured simultaneously and gravimetrically with two cyclone
136 samplers (URG Corp., Chapel Hill, N.C., U.S.) for PM₁₀ following CEN-EN 12341 (CEN,
137 1998). Samplers included the EU reference inlet in combination with a cyclone pre-separator.
138 A detailed description of samplers can be found in Zhao *et al.* (2009). After pre-separation
139 inside the cyclone, PM samples were collected on glass fibre filters (47 mm diameter, type
140 GF-3, Macherey-Nagel, Duren, Germany). Sampled air was drawn into the sampler at an
141 airflow rate of 16.7 L min⁻¹ using stationary pumps (Charlie HV, Ravebo Supply B.V.,
142 Brielle, the Netherlands). The pumps were able to keep a constant airflow using a temperature
143 sensor at the same position as the inlet of the cyclone PM collector. The volume of air passing
144 through the cyclones was measured by a gas meter within the pump and corrected for the
145 temperature measured at the sampling point.

146 Unloaded filters were stabilized for 48 h under standard conditions (20°C ± 1°C temperature
147 and 50%±5% relative humidity). Each filter was then weighed four times using a precise
148 balance (AT261 DeltaRange, Mettler, Greifensee, Switzerland; resolution: 10 µg), following
149 CEN-EN 14907 (CEN, 2005). The average value was calculated as the filter weight. For the
150 loaded filters, the same weighing procedure was adopted. The weight difference between
151 loaded and unloaded filters equaled the amount of collected PM. The PM concentrations were
152 calculated as the mass of collected PM divided by the volume of air drawn through the filter.
153 Average of duplicate cyclone measurements was used for calculations.

154 **2.3. Sampling sites**

155 Sampling was conducted in 32 animal houses in the Netherlands: 16 houses for poultry
156 including broilers, broiler breeders, layers in floor and in aviary systems, and turkeys; and 16

157 houses for pigs, including piglets, growing-finishing pigs in traditional and low emission
 158 housing with dry and liquid feed, and sows in individual and group housing. Table 1 describes
 159 the sampling sites. Co-located sampling instruments (one DustTrak and two cyclone
 160 samplers) in each animal house were positioned with the inlets of both instruments at a
 161 horizontal distance of 0.5 m from the border of the exhaust opening and at a vertical distance
 162 of 0.10 m underneath the exhaust opening (in buildings with room ventilators); and in front of
 163 the ventilators at a horizontal distance of approximately 2–3 m (air velocity <math><2\text{ m s}^{-1}</math>;
 164 allowing non-isokinetic PM sampling) (in buildings with tunnel ventilation). Sampling
 165 duration was 24 h (from noon to noon). During measurements, environmental indoor
 166 temperature and relative humidity were registered. More details of sampling sites, position,
 167 and measurement methods are described in Winkel *et al.* (2014).

168 Table 1. Description of sampling sites and number of samples.

Animal species	Housing system		Number of houses	Number of samples	Ventilation system	Number of animals per house
Poultry	Broilers	Litter floor	4	13	Tunnel	19,000-52,000
	Broiler breeders	Litter and slatted floor	2	8	Tunnel	8,121-10,253
	Laying hens - floor	Litter and slatted floor	4	14	Tunnel or roof (2 houses each)	4,300-17,500
	Laying hens - aviary	Litter and aviaries	4	13	Tunnel	10,900-36,900
	Turkeys	Litter floor	2	7	Tunnel	4,500-5,000
Pigs	Piglets	Fully or partially slatted floor (2 houses each)	4	17	Ceiling fans	75-130
	Growing-finishing pigs - traditional	Partially slatted floor	4	13	Ceiling fans	55-120
	Growing-finishing pigs - low emission, dry feed	Partially slatted floor, pit with slanted walls and sewage pipe	2	9	Ceiling fans	132-144
	Growing-finishing pigs - low emission, liquid feed	Partially slatted floor, pit with slanted walls and sewage pipe	2	9	Ceiling fans	144-156
	Dry and pregnant sows - individual housing	Confined gestation stalls (solid and slatted floor)	2	10	Ceiling fans	32-135
	Dry and pregnant sows - group housing	Free access to gestation stalls (solid and slatted floor)	2	6	Ceiling fans	39-44

169

170 **2.4. Data analyses**

171 A total of 119 pairs of 24 h measurements (55 for poultry and 64 for pigs) were recorded and
172 analyzed using linear regression analysis. Linear regression was conducted separately for each
173 animal species (poultry and pigs). In all cases, the PM10 concentration measured during 24 h
174 using cyclone samplers was used as independent variable, whereas the PM10 concentration
175 measured using the DustTrak was used as the dependent variable following equation 1.

176 $y = \beta_1 x + \beta_0$ Equation 1

177 where: β_1 is the slope and β_0 is the intercept. A significance level of 0.05 was used for all
178 statistical tests. According to Cheng (2008), regression intercepts significantly different from
179 zero were considered to indicate systematic bias of PM concentrations between samplers.
180 Regression slopes significantly different from one were considered to indicate proportional
181 bias of PM concentrations between samplers. The coefficient of determination (R^2) was used
182 to describe the correlation of measured PM concentrations between samplers. Data were
183 analyzed using SAS Software (SAS, 2001).

184 We also analyzed absolute and relative deviations associated with these samplers. The
185 absolute deviation between the DustTrak and cyclone sampler was calculated for poultry and
186 pig dataset following equation 2, as the difference between both samplers. The relative
187 deviation between the DustTrak and cyclone sampler was calculated for poultry and pig
188 dataset following equation 3. This deviation was multiplied by 100, to express it in
189 percentage, varying from -100% to 100%. Besides these deviations, random deviations
190 independent from systematic and proportional bias were calculated as the difference between
191 the reference cyclone PM10 concentration and the modeled PM10 concentration calculated
192 from applying each regression equation to poultry and pig data separately following equation
193 4. Random deviations were calculated independent from the fact that reference samplers
194 could also attribute by their own random deviations to this term.

195 $Absolute\ deviation = Cyclone\ PM10\ concentration - DustTrak\ PM10\ concentration$ Equation 2

196 $Relative\ deviation\ (%) = \left(\frac{Absolute\ deviation}{Cyclone\ PM10\ concentration} \right) \times 100$ Equation 3

197 $Random\ deviation = DustTrak\ observed\ PM10\ concentration - Modeled\ DustTrak\ PM10\ concentration$

198 Equation 4

199 **3. Results**

200 **3.1. Environmental conditions and PM10 concentrations**

201 During measurements, PM10 concentrations inside animal houses, measured with cyclone
 202 samplers, were higher in poultry than in pig houses. In poultry houses, indoor PM10
 203 concentrations ranged from 0.47 to 8.45 mg m⁻³ (average 2.52 mg m⁻³); whereas in pig
 204 houses, indoor PM10 concentrations ranged from 0.18 to 1.88 mg m⁻³ (average 0.76 mg m⁻³).
 205 Indoor temperature and relative humidity in the animal houses during the measurements are
 206 shown in Table 2. Further details of environmental conditions during sampling (indoor
 207 inhalable and PM2.5 concentration, outdoor temperature and relative humidity and ventilation
 208 rates) can be found in Winkel *et al.* (2014).

209 Table 2. Average indoor temperature (°C) and relative humidity (%) and range in brackets,
 210 during measurements.

Animal species and housing system	Temperature	Relative humidity
Broilers	22.8 (18.0-29.1)	69.5 (55.7-86.4)
Broiler breeders	21.7 (20.2-22.3)	72.8 (65.1-90.3)
Laying hens - floor	19.9 (16.2-24.0)	67.4 (58.0-74.4)
Laying hens - aviary	21.5 (19.2-25.6)	62.5 (51.4-92.9)
Turkeys	21.6 (20.1-23.6)	68.4 (65.3-73.4)
Piglets	26.4 (24.4-29.4)	54.6 (41.2-69.1)
Growing-finishing pigs - traditional	24.8 (20.1-28.0)	56.5 (41.0-73.8).
Growing-finishing pigs - low emission, dry feed	25.2 (23.2-27.9)	54.8 (44.0-78.0)
Growing-finishing pigs - low emission, liquid feed	24.9 (22.3-26.1)	55.6 (45.1-69.3)
Dry and pregnant sows - individual housing	21.2 (18.1-24.0)	59.8 (43.3-74.3)
Dry and pregnant sows - group housing	22.0 (19.4-24.8)	67.9 (56.5-84.0)

211

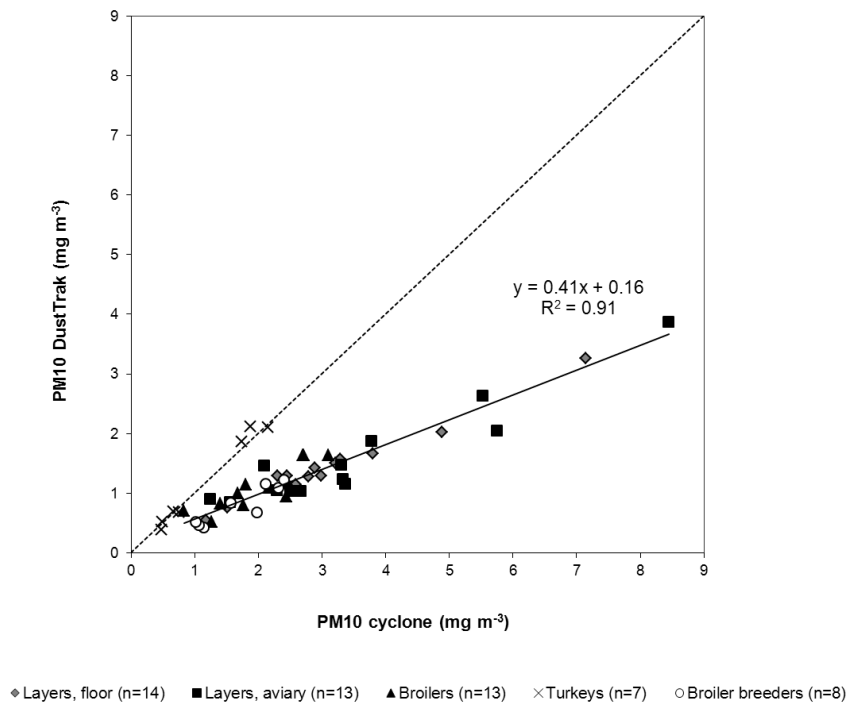
212

213

214 **3.2. Comparison between samplers**

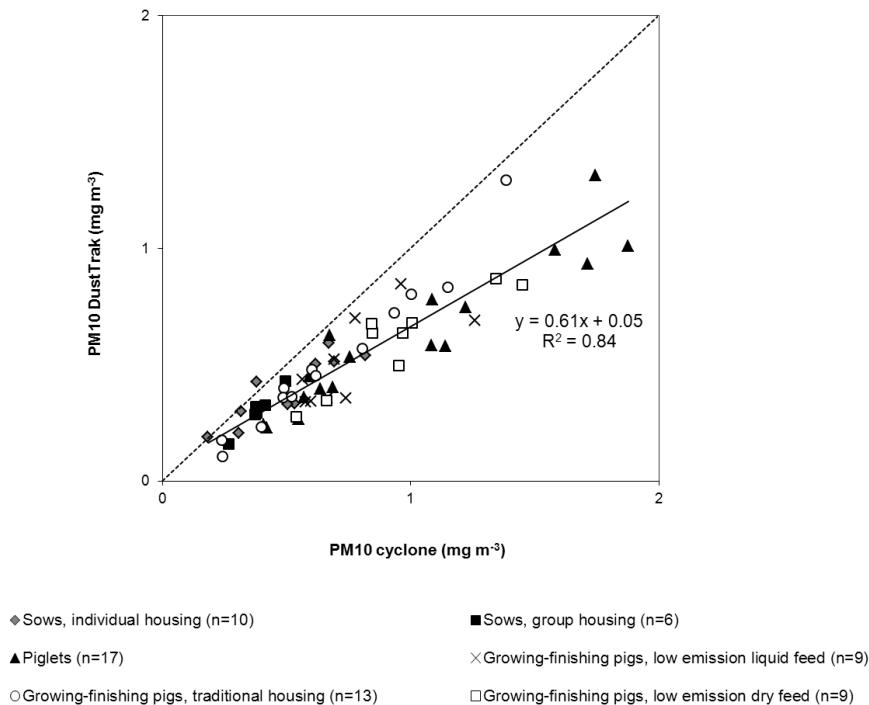
215 The linear response of DustTrak to PM10 concentrations measured with cyclone samplers
216 showed a clear proportional and systematic bias which varied slightly among animal species.
217 In poultry, cyclone and DustTrak data fitted well to a linear regression line ($P < 0.0001$), with a
218 regression coefficient equal to 0.41 ($P = 0.008$; test for difference from 1), an intercept of 0.16
219 mg m^{-3} ($P < 0.0001$; test for difference from 0) and a correlation coefficient of 0.91 (excluding
220 turkeys) (Figure 1). Results in turkeys showed a different trend, with a regression coefficient
221 equal to 1.1 ($P = 0.49$), an intercept of 0.06 mg m^{-3} ($P < 0.0001$) and a correlation coefficient of
222 0.98.

223 In pigs, cyclone and DustTrak data also fitted well to a linear regression line ($P < 0.0001$), with
224 a regression coefficient equal to 0.61 ($p = 0.07$), an intercept of 0.05 mg m^{-3} ($P < 0.0001$) and a
225 correlation coefficient of 0.84 (Figure 2).



226

227 Figure 1. Relationship between light scattering DustTrak and cyclone sampler for PM10
 228 concentrations in poultry houses. The dashed line represents $y=x$.



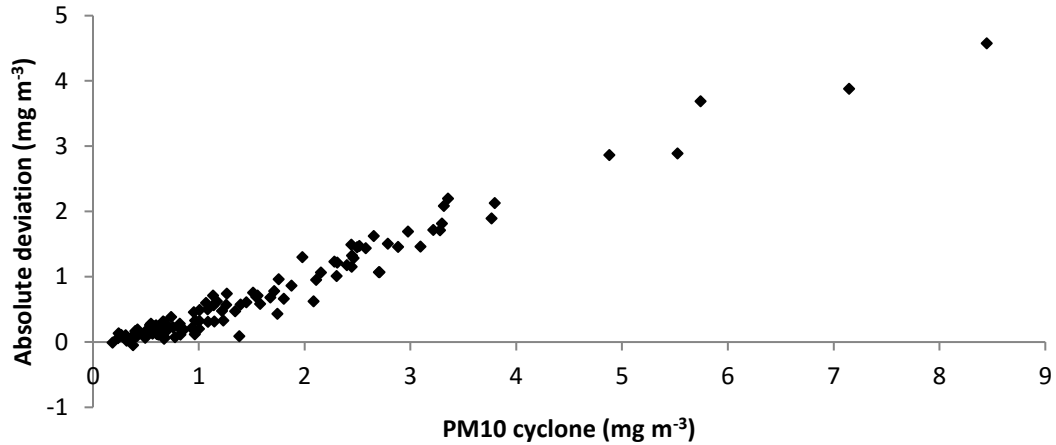
229

230 Figure 2. Relationship between light scattering DustTrak and cyclone sampler for PM10
 231 concentrations in pig houses. The dashed line represents $y=x$.

232 **3.3. Deviations between samplers**

233 Figure 3 shows the distribution of absolute deviations within the whole data set (excluding
 234 turkeys). Absolute deviations varied from -0.05 to 4.57 mg m^{-3} and increased linearly with
 235 PM10 concentration. Average absolute deviation equaled 0.75 mg m^{-3} .

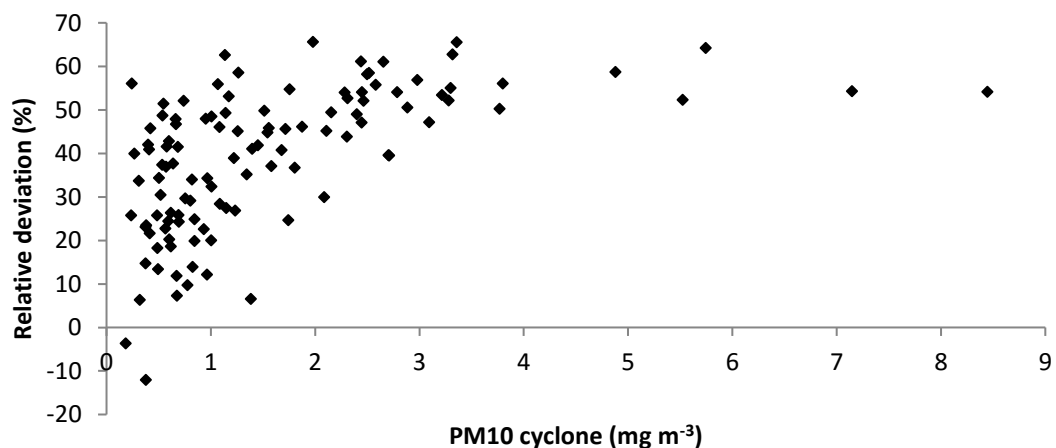
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237

238 Figure 3. Absolute deviation (mg m^{-3}) between DustTrak and cyclone sampler for poultry and
 239 pig dataset ($n= 112$, excluding turkeys), as a function of PM10 concentrations measured with
 240 cyclone sampler.

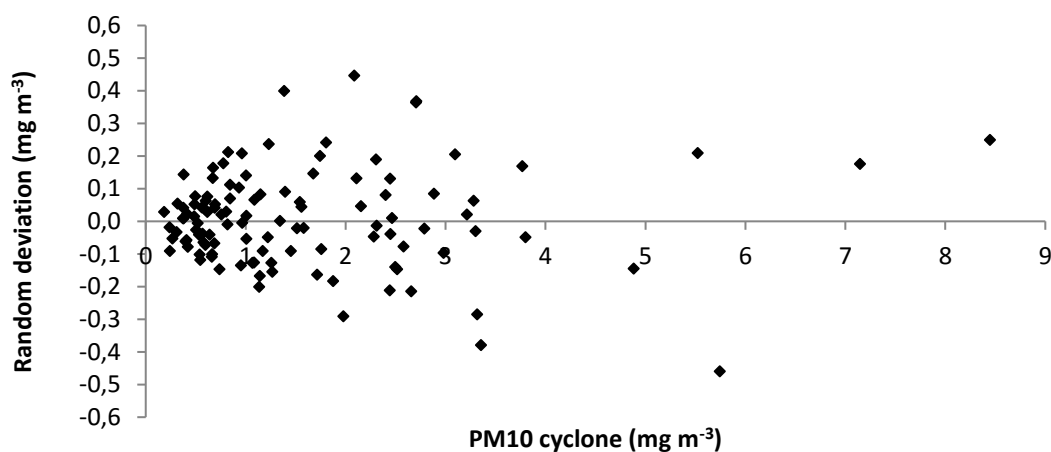
241 As regards relative deviations, Figure 4 shows the distribution of relative deviations for
 242 poultry and pig dataset (excluding turkeys). Relative deviation varied from -12 to 66%, being
 243 on average 39%. Relative deviation increased with PM10 concentration. The distribution of
 244 this deviation resembled a logarithmic curve. It showed a wide variation in the lowest
 245 concentrations ranges (below 2 mg m^{-3}) and was closer or exceeded the average relative
 246 deviation of 39% over 2 mg m^{-3} .



247

248 Figure 4. Relative deviation in percentage for poultry and pig dataset (n= 112, excluding
249 turkeys) between DustTrak and cyclone sampler as a function of PM10 concentrations
250 measured with cyclone sampler.

251 Figure 5 shows the distribution of random deviations for poultry and pig dataset (excluding
252 turkeys) based on the modeled DustTrak concentrations. Random deviations varied from -
253 0.46 to 0.45 mg m⁻³, being on average 0.01 mg m⁻³. Most frequent values were found between
254 -0.2 and 0.2 mg m⁻³. Random deviations increased with PM10 concentration, especially above
255 1 mg m⁻³.



256

257 Figure 5. Random deviation for poultry and pig dataset between observed and modeled
258 DustTrak PM10 concentration as a function of PM10 concentrations measured with cyclone
259 sampler.

260 Discussion

261 In the present comparative study, light-scattering devices showed a linear response to PM
262 from different animal housing systems. Our results indicate that DustTraks systematically
263 underestimate PM10 concentrations in pig and poultry houses by a factor of *circa*. 2 as
264 determined by cyclone samplers. This underestimation is probably caused by different
265 particle's properties of animal PM as compared to standard ISO 12103-1 Arizona Road Dust
266 (for which DustTraks are factory calibrated). Heal *et al.* (2000) determined that differences in
267 particle size distribution, shape and reflectance properties from the factory pre-set calibration

268 and the sampled airborne PM can produce different scattering responses for identical masses
269 of PM passing through the instrument. Light-scattering devices show high sensitivity and time
270 resolution, but scattering per unit mass is a strong function of particle size and refractive
271 index (Görner *et al.*, 1995). An explanation for this can be found in the measurement principle
272 of light-scattering devices, which is based on light scattering by airborne particles inside an
273 optical sensing volume. This depends on the Mie theory of light scattering and the built-in
274 optical parameters of such light-scattering photometers (Görner *et al.*, 1995).

275 Chung *et al.* (2001) reported that DustTraks are not calibrated to measure submicron particles,
276 but are calibrated with particles larger than 1 micrometer. The DustTrak cannot detect
277 particles with sized diameter smaller than 0.1 μm , and the amount of light scattered by
278 particles with diameter smaller than 0.25 μm is proportional to particle diameter raised to the
279 sixth power (D_p^6). These effects can cause the DustTrak measurements to differ from
280 gravimetric measurements of airborne particulate matter when the size distribution of the
281 airborne particles differs significantly from the size distribution of the test aerosol (Chung *et*
282 *al.*, 2001).

283 As opposed to the other poultry categories, no evident underestimation was found for turkeys.
284 Cambra-López *et al.* (2011a) reported that in turkey houses with ridge ventilation, PM could
285 partially originate from ambient air (outside source), whereas manure and feathers are the
286 most relevant sources of PM in broilers and hens, and manure and skin flakes the most
287 relevant sources in pigs. Ambient PM differs from PM found inside animal houses both in
288 morphology (smaller in size), chemical composition and size distribution (Cambra-López *et*
289 *al.*, 2011b), which may explain why DustTraks and cyclone samplers are in good agreement
290 for turkeys.

291 Conversely to our results, DustTraks tend to overestimate ambient PM concentrations
292 compared with gravimetric samplers by a factor of 1.4 to 3.0 (Cheng, 2008; Jenkins *et al.*,
293 2004). Cheng (2008) reported lower overestimations of DustTrak as particle size increased.
294 DustTrak provided a lower overestimation of PM₁₀ compared with PM_{2.5} (Cheng, 2008).

295 Lehocky and Williams (1996) suggested that at or below 1.1 mg/m^3 , DustTraks provided
296 higher values than gravimetric samplers, and this difference decreased as concentrations
297 exceeded 1.1 mg/m^3 , for coal dust. Differences in correlation or coefficient slopes might be
298 attributable to lower concentration range and PM composition (Yanosky *et al.*, 2002).

299 Liu *et al.* (2002) determined how PM sources related with cooking/frying activities within
300 households influenced the response of instruments. They also observed different responses
301 with high/low PM concentrations, concluding that their performance depends on the nature of
302 PM emissions. Thorpe and Walsh (2002) reported differences between flour dust (higher
303 variations in size) compared with pine or stone dust. These authors tested effects of dust
304 concentrations, dust composition, particle size, air velocity, monitor orientation and monitor
305 maintenance and cleaning. Contamination of the optics with dust often resulted in an increase
306 in monitor's response which decreased after cleaning. Among other factors influencing
307 DustTrak's response, Liu *et al.* (2002) identified that relative humidity played an important
308 role in particle volume and its light scattering properties. Moreover, further research on how
309 inherent particle properties and ambient relative humidity can influence light-scattering
310 properties of PM₁₀ in animal environments should be conducted.

311 An increase in DustTraks response with PM₁₀ concentration was observed in our study.
312 Absolute, relative, and random deviations increased with concentration. According to
313 Kingham *et al.* (2006), over-reading with DustTraks is probable, and these over-recording is
314 usually higher with increasing PM₁₀ concentrations. Van Ransbeeck (2013) reported
315 increasing differences between real-time photometers and gravimetric sampler for PM₁₀
316 concentrations (in the range between 0.02 to 2.29 mg m^{-3}). Optical light scattering instruments
317 are more sensitive at low concentrations. This is because it is easier to detect a change in a
318 small light intensity than in an intensity which is already very bright (VINCENT, 2007). On
319 the other hand, smaller particles usually scatter more light and so the response of DustTraks
320 might increase with decreasing particle size (Visser *et al.*, 2006).

321 The lack of adequately standardized monitoring devices for PM sampling has biased PM
 322 quantification in animal houses. If true mass has to be measured using light-scattering
 323 photometers, animal-specific calibration factors are necessary and measured PM
 324 concentrations need to be corrected. Therefore, it is essential to firstly, calibrate these devices
 325 to obtain reliable calibration factors, and secondly, to correct data by applying these
 326 calibration factors. Jenkins *et al.* (2004) identified two calibration options: in the laboratory
 327 with equivalent aerosol or on-field. On-field calibration was conducted in our study to obtain
 328 linear regression calibration equations per animal species.

329 The DustTrak's manual, however, recommends using custom calibration factors to correct
 330 real-time PM10 mass concentrations. Custom calibrations factors can be calculated by simply
 331 dividing reference PM10 concentration measured with the cyclone sampler by the PM10
 332 concentration measured with the DustTrak sampler following equation 5.

$$333 \text{ Calibration factor} = \frac{\text{Cyclone PM10 concentration}}{\text{DustTrak PM10 concentration}} \quad \text{Equation 5}$$

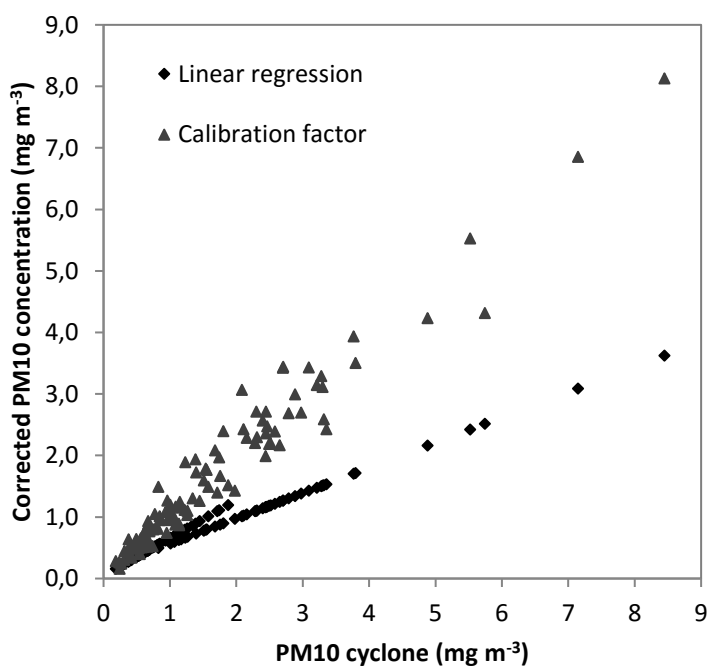
334 An example of custom calibration factors for DustTrak calculated following equation 5, for
 335 our dataset is presented in Table 3. These values resulted in lower calibration factors for pigs
 336 compared with poultry, being on average equal to 2.1 for poultry and 1.5 in pigs (Table 3). In
 337 turkeys, calibration factor equaled 1.0.

338 Table 3. DustTrak calibration factors for each studied animal species and housing systems.

Animal species and housing system	Calibration factor
Broilers	1.9
Broiler breeders	2.2
Laying hens - floor	2.1
Laying hens - aviary	2.2
Turkeys	1.0
Average poultry (except for turkeys)	2.1
Piglets	1.6
Growing-finishing pigs - traditional	1.4
Growing-finishing pigs - low emission, dry feed	1.6
Growing-finishing pigs - low emission, liquid feed	1.6
Dry and pregnant sows - individual housing	1.3
Dry and pregnant sows - group housing	1.3
Average pigs	1.5

339

340 Figure 6 presents corrected real-time PM10 mass concentration using linear regression
341 equations and custom calibration factors for our data set (excluding turkeys) (Figure 6). This
342 figure shows that above 1 mg m⁻³, corrected PM10 concentration using custom calibration
343 factors was higher than using linear regression equation. This difference is attributable to the
344 intercept (systematic bias) in regression equations, which pulled down the corrected values.
345 Therefore, for correcting PM data form poultry and pig houses, we recommend linear
346 regression equations as animal-specific calibration factors for DustTraks instead of
347 manufacturer calibration factors, especially in heavily dusty environments such as animal
348 houses where PM10 concentrations above 1 mg m⁻³ are common.



349

350 Figure 6. Comparison between corrected DustTrak PM10 concentration using linear
351 regression modeling and custom calibration factors for poultry and pig dataset (n= 112,
352 excluding turkeys).

353 Standardized measuring protocols to measure PM levels in different size fractions need to be
354 developed and harmonization is needed. DustTraks are useful to measure relative PM, but not
355 absolute values (Park *et al.*, 2009). These instruments are suitable where only relative values
356 are required (Kuusisto, 1983). Direct-reading instruments are better adapted to time and space

357 monitoring than for exposure assessment. Therefore, they complement traditional gravimetric
358 techniques rather than replace. Nevertheless, they are very suitable to evaluate PM control
359 measures (Görner *et al.*, 1995).

360 Moreover, they are easy to operate, portable, and provide a continuous output of instant time-
361 resolved data at a relatively low cost. Consequently, the characteristics of real-time samplers
362 result in advantages compared with gravimetric samplers; and although gravimetric samplers
363 are recognized as the standard method and provide accurate time-averaged measurements
364 independent from particle characteristics, they have some disadvantages compared to light
365 scattering photometers, they require weighing filters on an analytical balance, and can only
366 provide cumulative mass concentration results 24-48 h after conducting measurements on-
367 field. These facets, in combination with reliable correction factors, could allow the DustTrak
368 to be used in cost effective and low maintenance monitoring networks (Kingham *et al.*, 2006).

369 The regression equations obtained per animal category can be used in the future to correct
370 real-time PM10 mass concentrations measured using DustTraks. (to improve precision
371 compared with gravimetric data). If DustTraks are to be used to verify exceedance of certain
372 thresholds or in exposure assessment studies, especial care should be taken in interpreting
373 results (Liu *et al.*, 2002).

374

375 **Conclusions**

376 Paired DustTrak light scattering device (DustTrak aerosol monitor, TSI, U.S.) and PM10
377 gravimetric cyclone sampler were used for measuring PM10 mass concentrations during 24 h
378 periods (from noon to noon) inside animal houses. Sampling was conducted in 32 animal
379 houses in the Netherlands, including broilers, broiler breeders, layers in floor and in aviary
380 system, turkeys, piglets, growing-finishing pigs in traditional and low emission housing with
381 dry and liquid feed, and sows in individual and group housing. A total of 119 pairs of 24 h
382 measurements (55 for poultry and 64 for pigs) were recorded and analyzed using linear
383 regression analysis. The following conclusions can be drawn:

- 384 • Measured PM10 concentrations using DustTraks were clearly underestimated
385 (approx. by a factor 2) in both poultry and pig housing systems compared with
386 cyclone pre-separators. Absolute, relative, and random deviations increased with
387 concentration.
- 388 • In poultry, cyclone and DustTrak data fitted well to a linear regression line
389 ($P < 0.0001$), with a regression coefficient equal to 0.41 ($P = 0.008$; test for difference
390 from 1), an intercept of 0.16 mg m^{-3} ($P < 0.0001$; test for difference from 0) and a
391 correlation coefficient of 0.91 (excluding turkeys).
- 392 • In pigs, cyclone and DustTrak data also fitted well to a linear regression line
393 ($P < 0.0001$), with a regression coefficient equal to 0.61 ($p = 0.07$), an intercept of 0.05
394 mg m^{-3} ($P < 0.0001$) and a correlation coefficient of 0.84.
- 395 • DustTraks results should be interpreted carefully to quantify PM10 in animal houses,
396 when appropriate calibration factors are not used. The regression equations obtained
397 per animal category can be used in the future to correct real-time PM10 mass
398 concentrations measured using DustTraks. We recommend linear regression
399 equations as animal-specific calibration factors for DustTraks instead of manufacturer
400 calibration factors, especially in heavily dusty environments such as animal houses
401 with PM10 concentrations exceeding 1 mg m^{-3} .

402

403 **Acknowledgements**

404 The study was financed by the Dutch Ministry of Economic affairs, Agriculture and
405 Innovation. Authors wish to thank the Campus de Excelencia Internacional of the Universitat
406 Politècnica de València (Spain) for funding Dr. Cambra-López's postdoc contract.

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